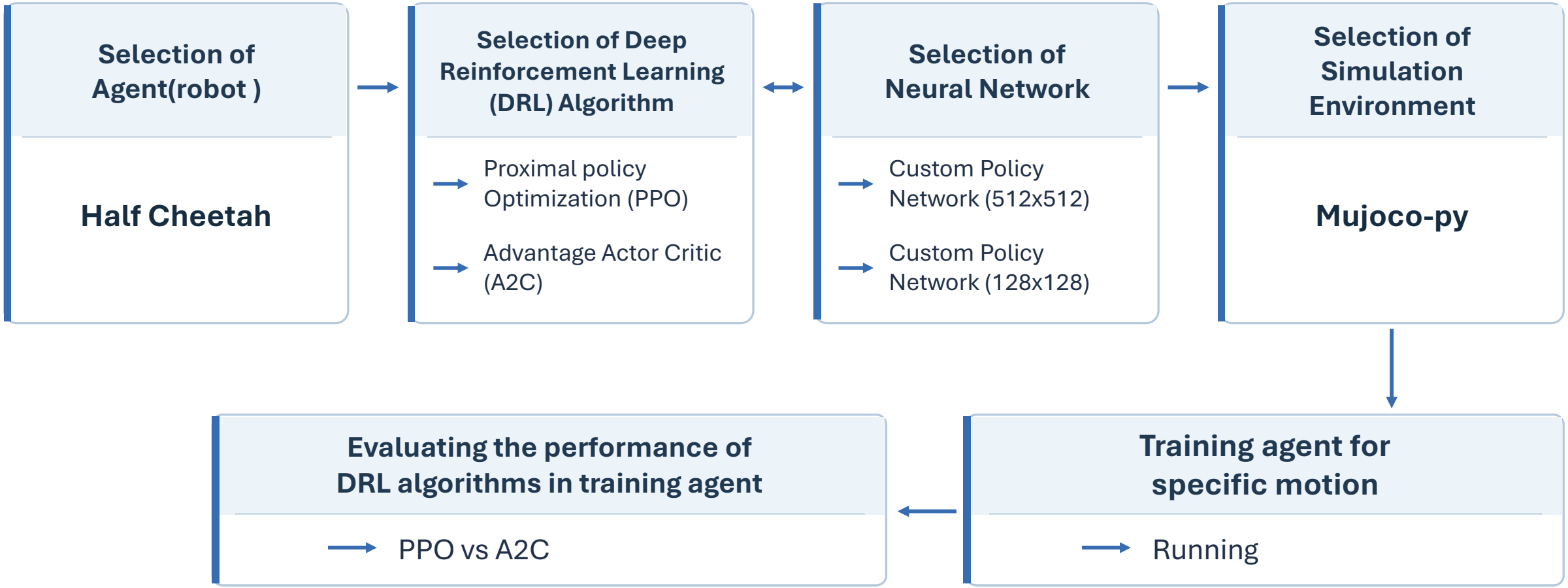
Selection of Agent(robot)
Half Cheetah
Selection of Deep Reinforcement Learning (DRL) Algorithm
Proximal policy Optimization (PPO)
Advantage Actor Critic (A2C)
Selection of Neural Network
Custom Policy Network (512x512)
Custom Policy Network (128x128)
Selection of Simulation Environment
Mujoco-py
Training agent for specific motion
Running
Evaluating the performance of DRL algorithms in training agent
PPO vs A2C